

CS-200

Computer Architecture

Part 5a. Multiprocessors

Cache Coherence

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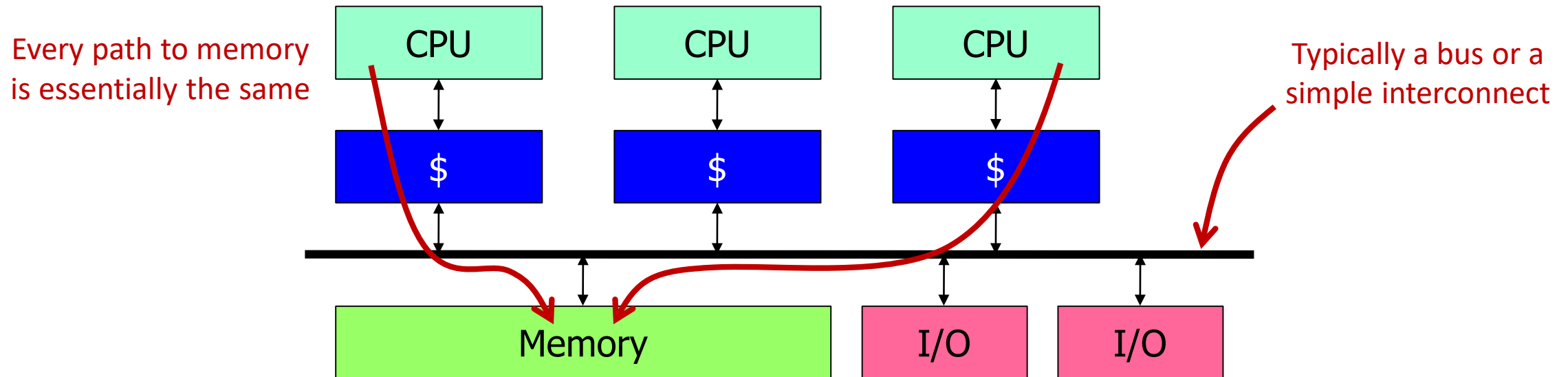
Flynn's Taxonomy (1966)

Single/Multiple Instruction Streams (= programs)

Single/Multiple Data Streams

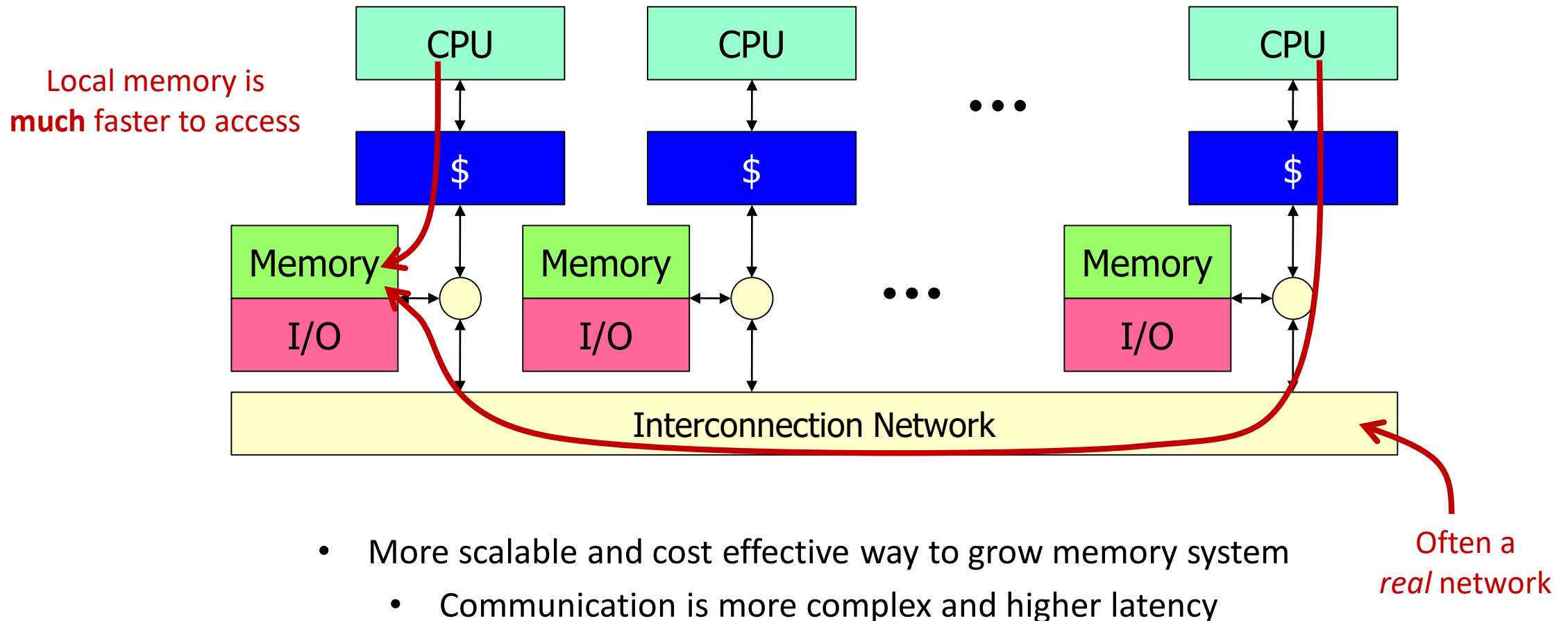
- **SISD**: Uniprocessors, what we have seen so far
- **SIMD**: A single program is run on multiple data sets at once. Classic examples are Vector Architectures for high-performance computing, now fairly rare. More commonly, x86 supports SIMD through various ISA extensions: MMX (1996), SSE (1999-2008), and AVX (2011-2016)
- **MIMD**: General form of parallelism with each processor executing its own program on its own data

Shared-Memory Multiprocessors (UMA = Uniform Memory Access)



- Limited scalability (4-16 processors?)
- Very simple and fairly traditional architecture

Distributed-Memory Multiprocessors (NUMA = Nonuniform Memory Access)



Programming Paradigms

- **Shared-Memory**

- Data exchanged **implicitly** through shared variables in a common memory space
- Standard libraries (e.g., **OpenMP**) simplify programming
- Natural on shared-memory architectures (e.g., **SMP**, **NUMA**)
- Can be implemented as **Distributed Shared Memory (DSM)** on systems with physically distributed memory, leveraging virtual memory abstractions (e.g., **TreadMarks** for DSM; **Apache Spark** for a DSM-like abstraction in big data)

- **Message Passing**

- Data exchanged **explicitly** by sending and receiving messages over a network or interconnect
- Standard libraries (e.g., **MPI**) are widely used
- Natural on distributed-memory systems with private memory per processor
- Can also be implemented on shared-memory systems (e.g., **NUMA**), though it may introduce unnecessary overhead compared to native shared-memory programming

Why (Hardware) Shared Memory?

- **Advantages:**

- For applications looks like a multitasking uniprocessor
- For OS only evolutionary extensions required
- Easy to do communication without OS
- Software can worry about correctness first, then performance

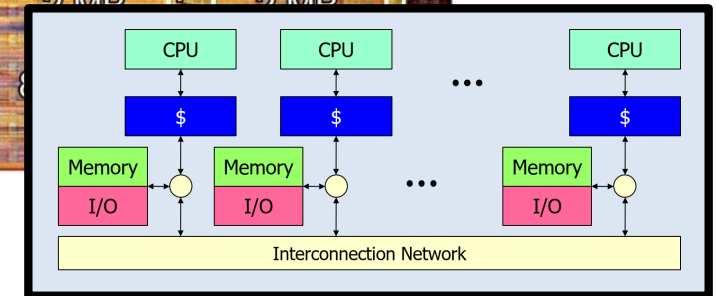
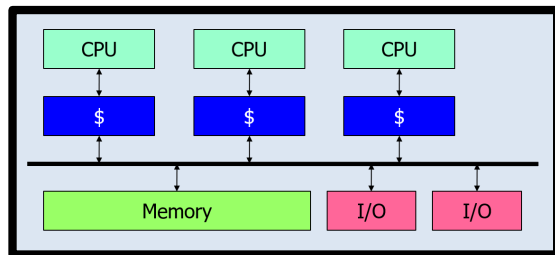
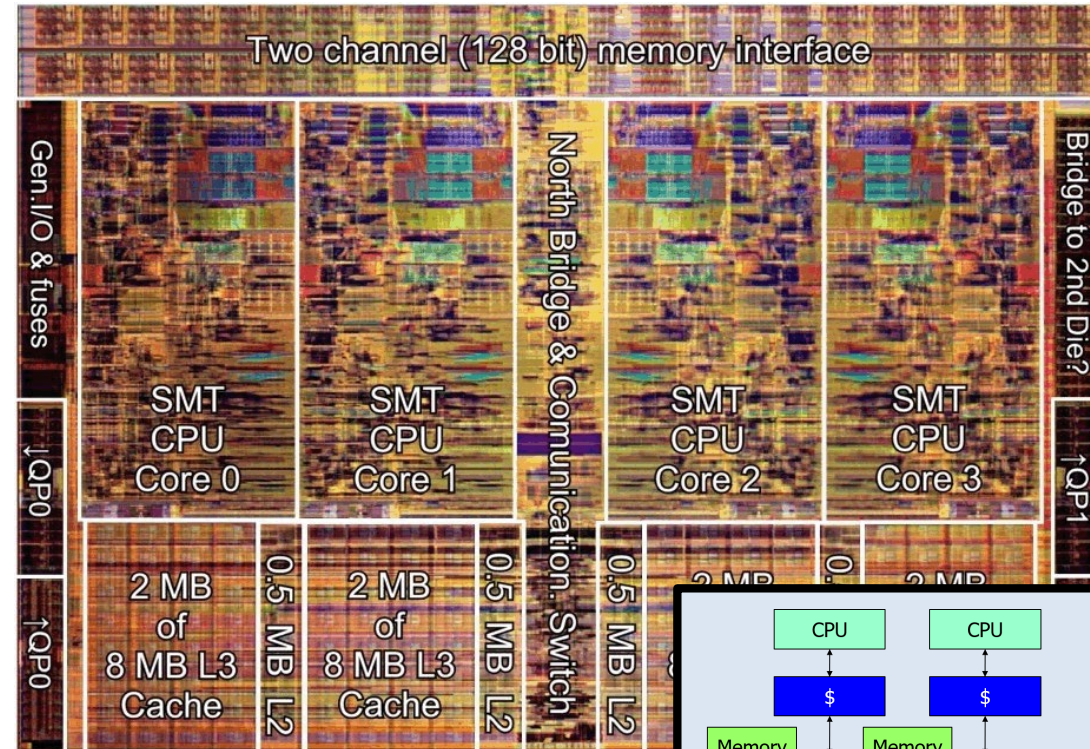
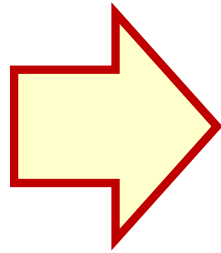
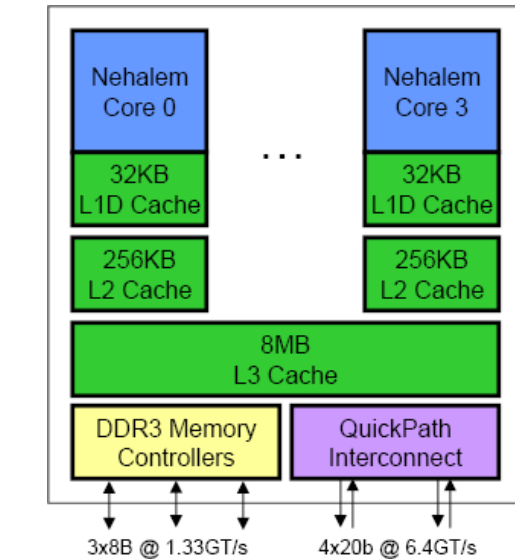
- **Disadvantages:**

- Communication is implicit, hence harder to optimize
- Proper synchronization is complex
- Hardware designers must implement

- **Result:**

- **Symmetric Multiprocessors (SMPs)** were the foundation of early supercomputers but gave way to distributed-memory message-passing systems as scaling issues made SMPs less efficient
- **Chip Multiprocessors (CMPs)** or **multicore** processors dominate as the most widespread form of parallel computing, driving multibillion-dollar markets

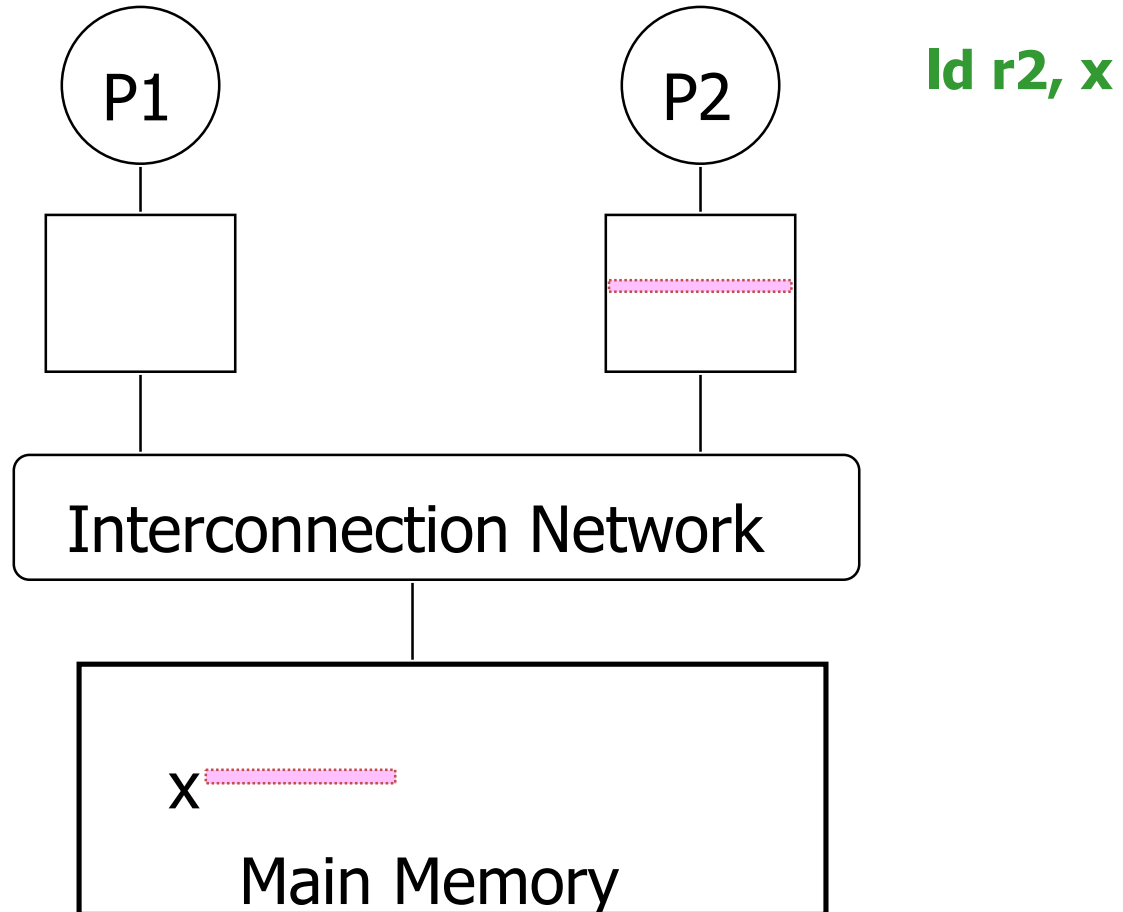
Intel Nehalem (2008)



Note that the L3 cache is **logically shared** but **physically distributed** across the four cores
→ even a **single CMP** is in fact **implemented** as a **NUMA** architecture

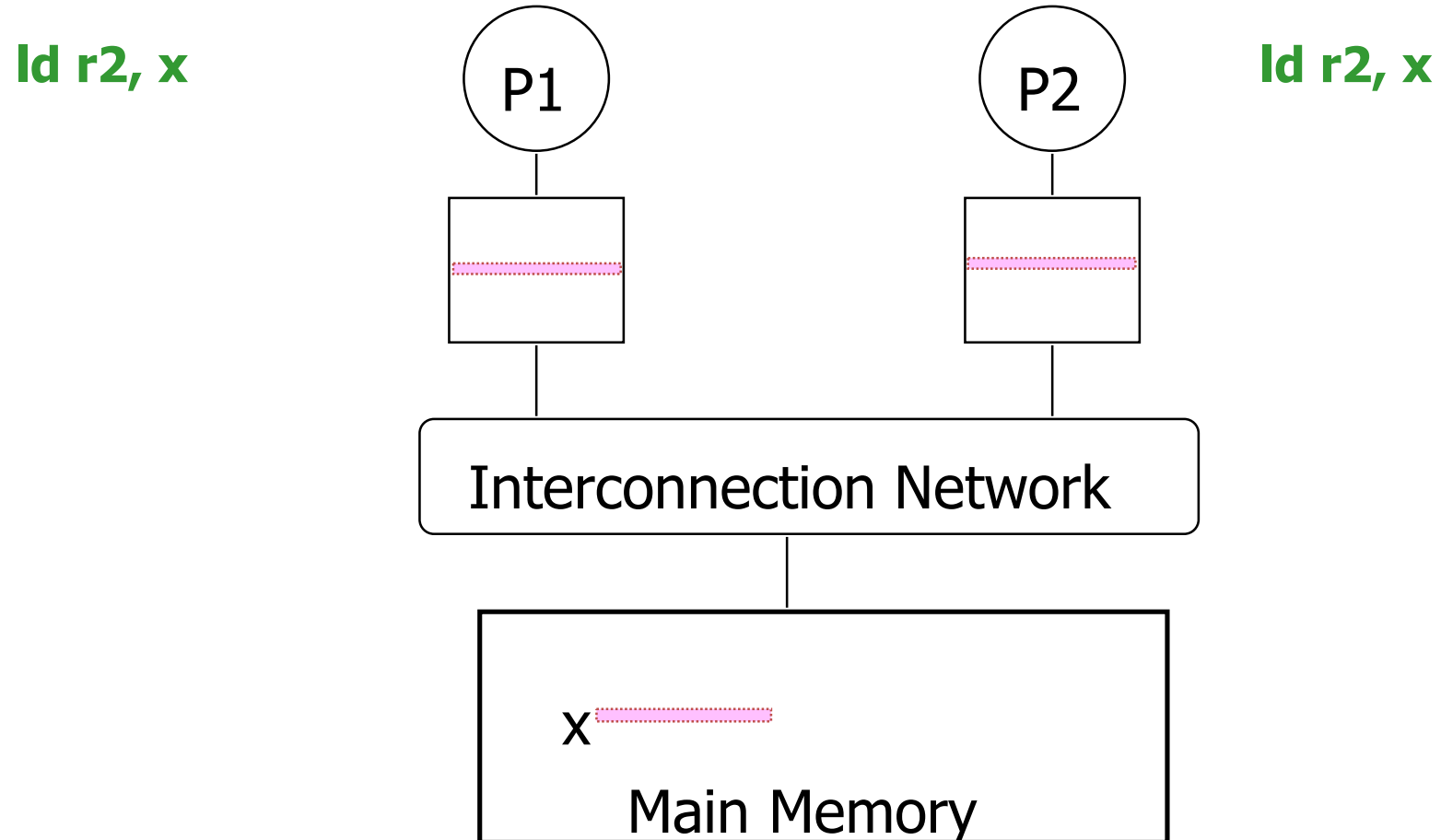
Cache Coherence Problem

Step 1



Cache Coherence Problem

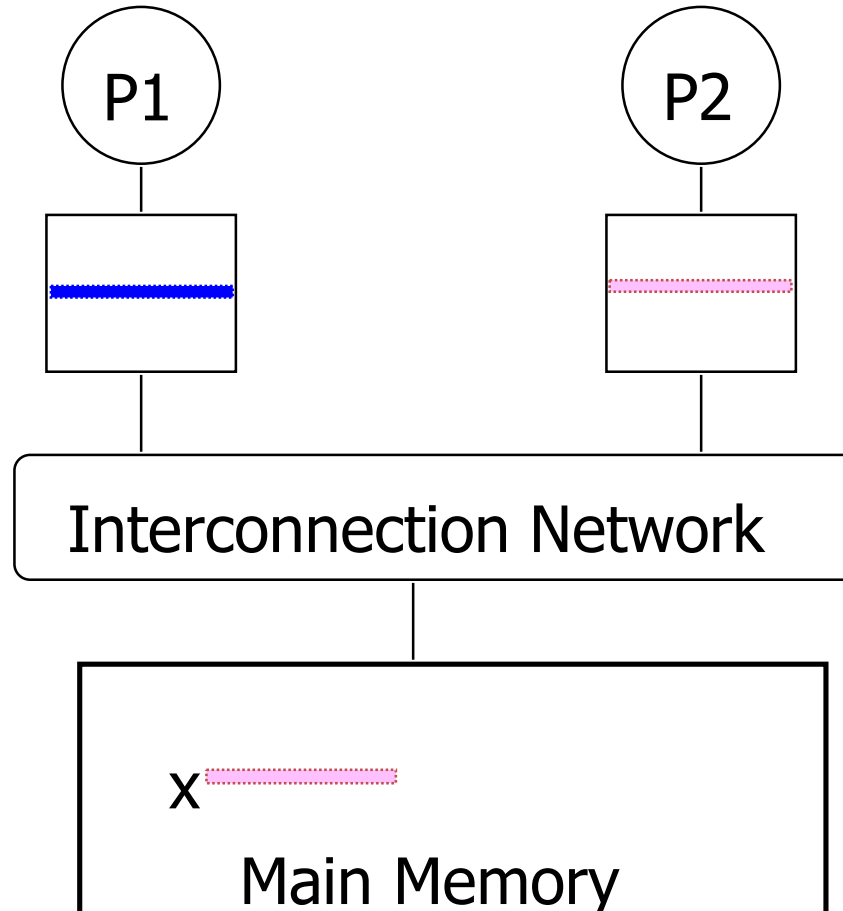
Step 2



Cache Coherence Problem

Step 3

ld r2, x
add r1, r2, r4
st x, r1

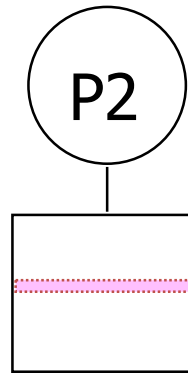
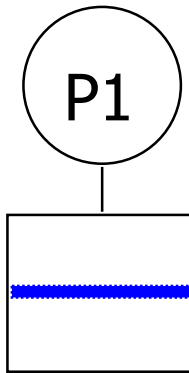


ld r2, x

Cache Coherence Problem

Step 4

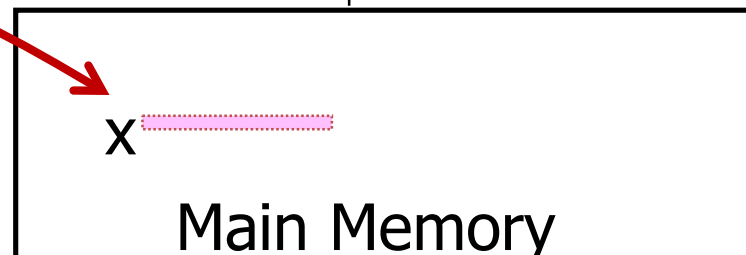
ld r2, x
add r1, r2, r4
st x, r1



ld r2, x
...
...
ld r5, x



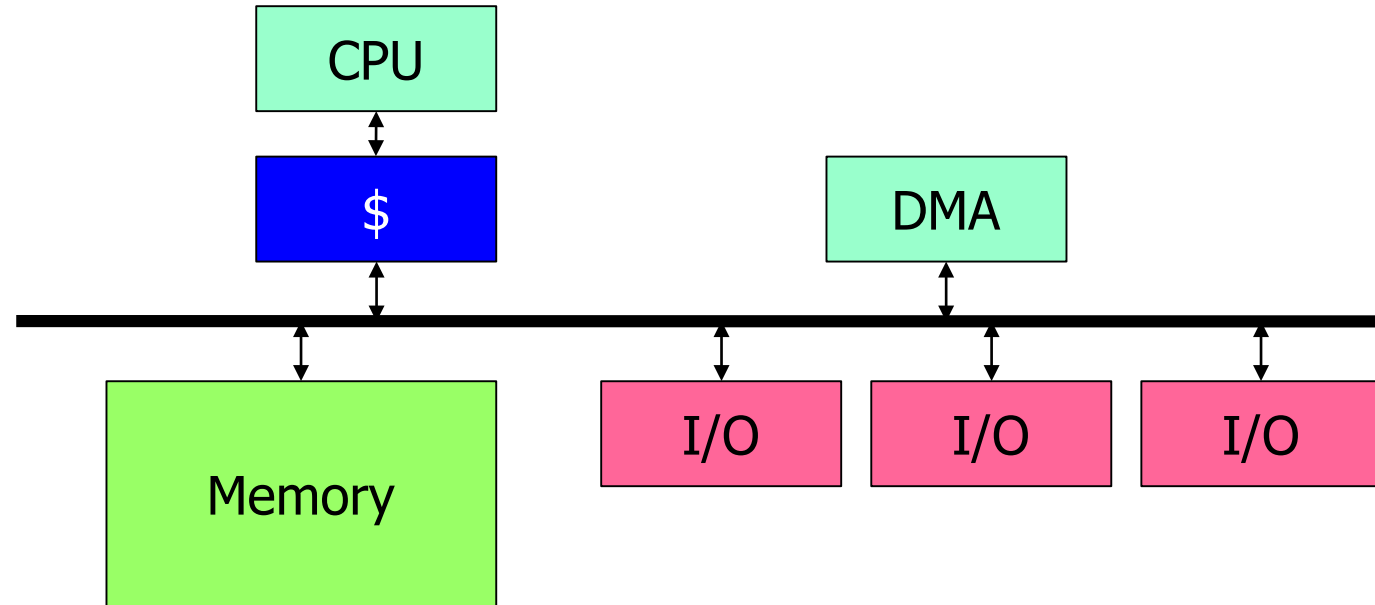
Interconnection Network



It is not a matter of
the cache not being
write-through!

Really New in Multiprocessors?

- Not really...



- But there we have simpler ad-hoc ways to handle this:
 - Flush the cache in software
 - Invalidate cache lines in software
 - Define **noncacheable areas of memory** and perform I/O there
 - ...

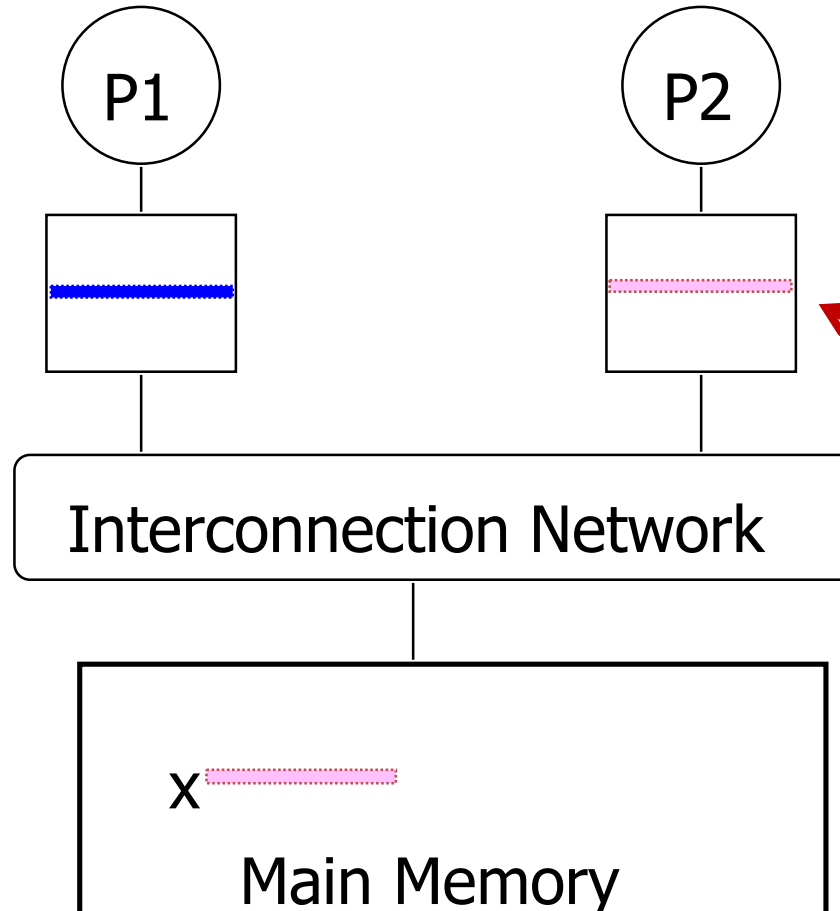
Coherent Memory System

1. **Preservation of program order.** If P writes in X and then P reads in X, and in the meantime no other processor has written X, the value returned is the value previously written by P
2. **Coherent view.** If P1 writes X and P2 reads X, and in the meantime no other processor has written X, the value returned is the value previously written by P1, if the read and write are *sufficiently separated in time*
3. **Write Serialization.** If P1 writes X and P2 writes X, all processors see the writes in the same order

Cache Coherence Problem

Step 4

ld r2, x
add r1, r2, r4
st x, r1



ld r2, x
...
...
ld r5, x



It is not a matter of giving **sufficient** time!

Snoopy Cache-Coherence Protocols

- Bus provides serialization point (more on this later)

- Each cache controller **snoops** all bus transactions

- Relevant transactions if for a **line of cache** it contains
- Take appropriate action to ensure coherence

- Invalidate
- Update
- Supply value

- Which one depends on state of the line and the protocol

Unit of data in a cache

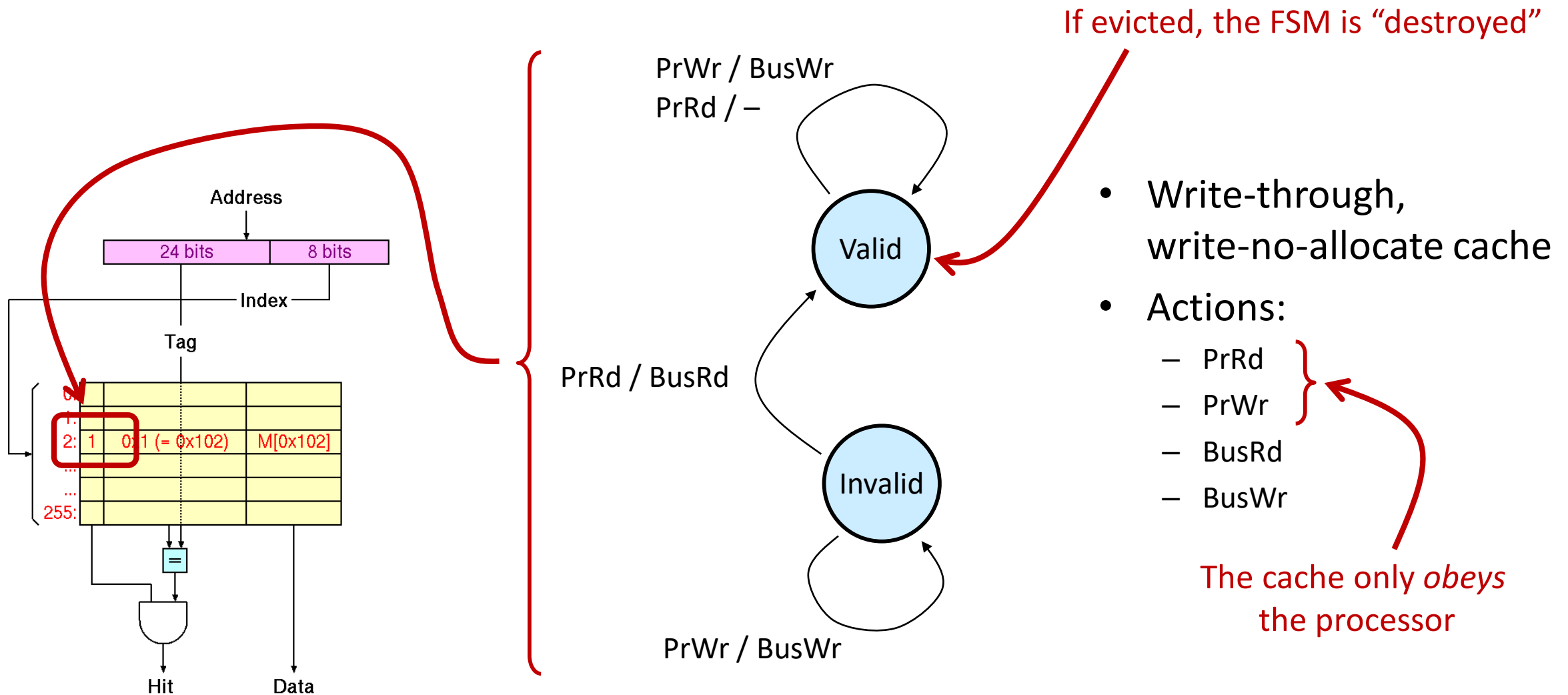
Cache
FSMs

Simultaneous operation of independent controllers

FSM of a Cache

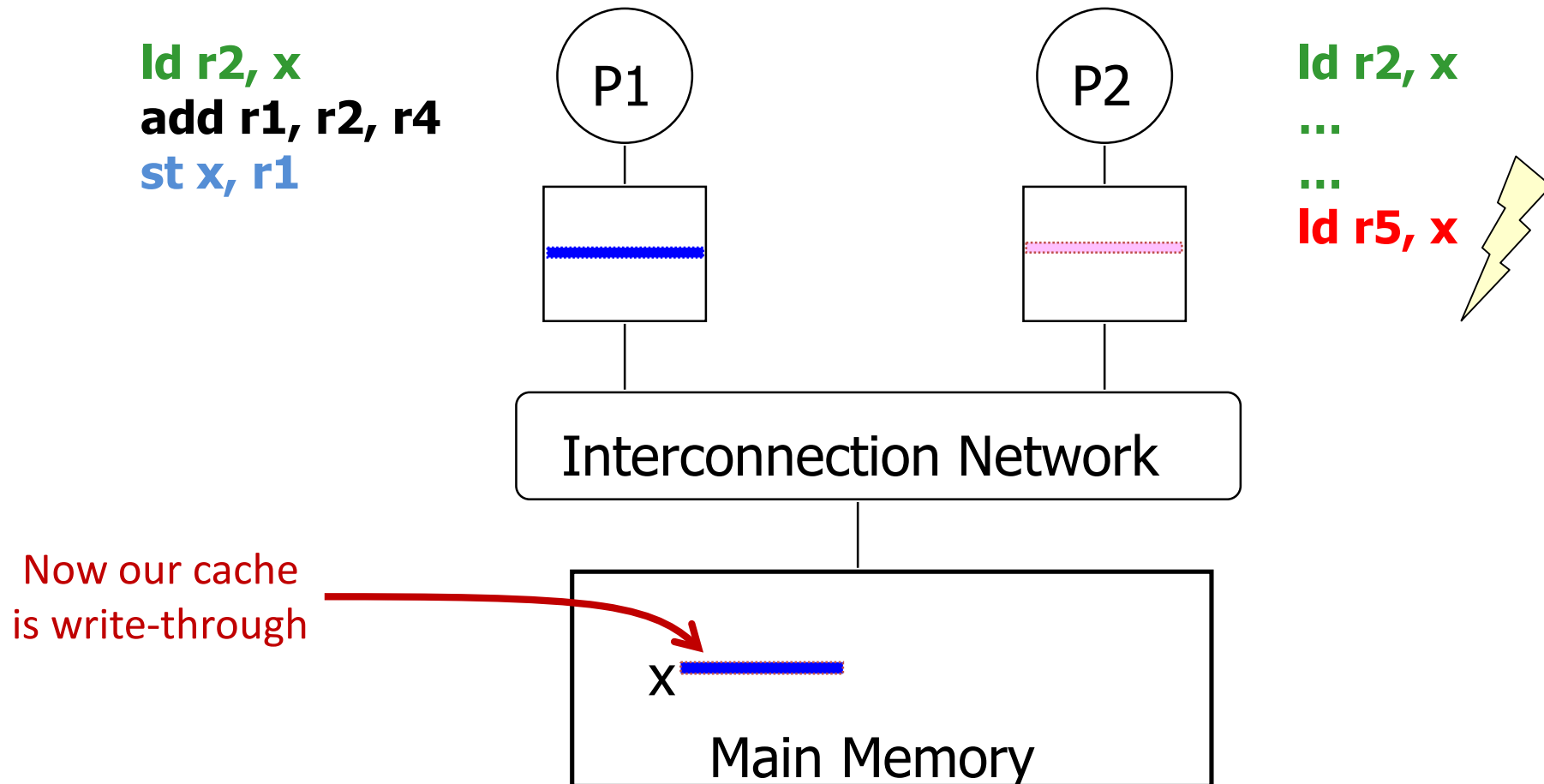
- Write-through,
write-no-allocate cache
- Actions:
 - PrRd
 - PrWr
 - BusRd
 - BusWr

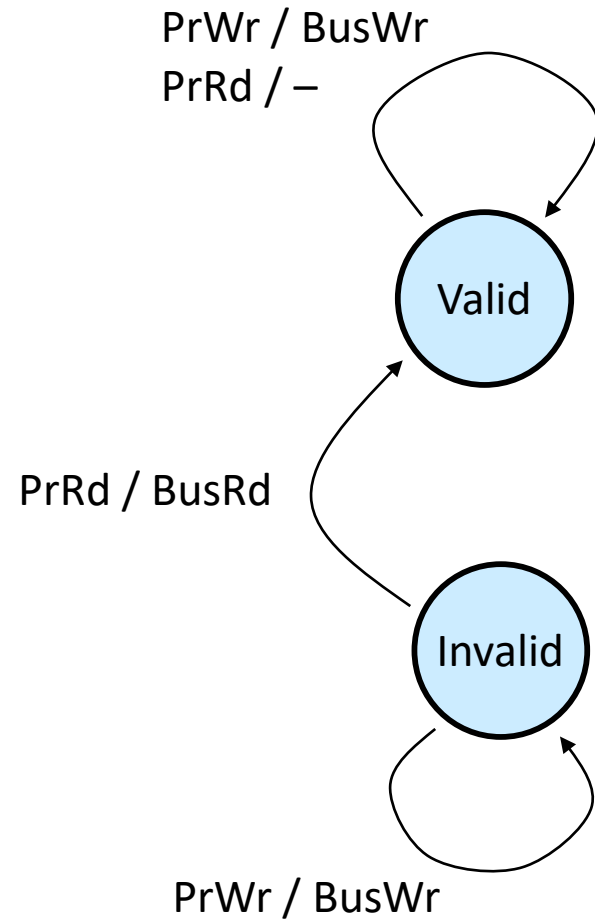
The FSM of a Simple Cache Protocol



Cache Coherence Problem

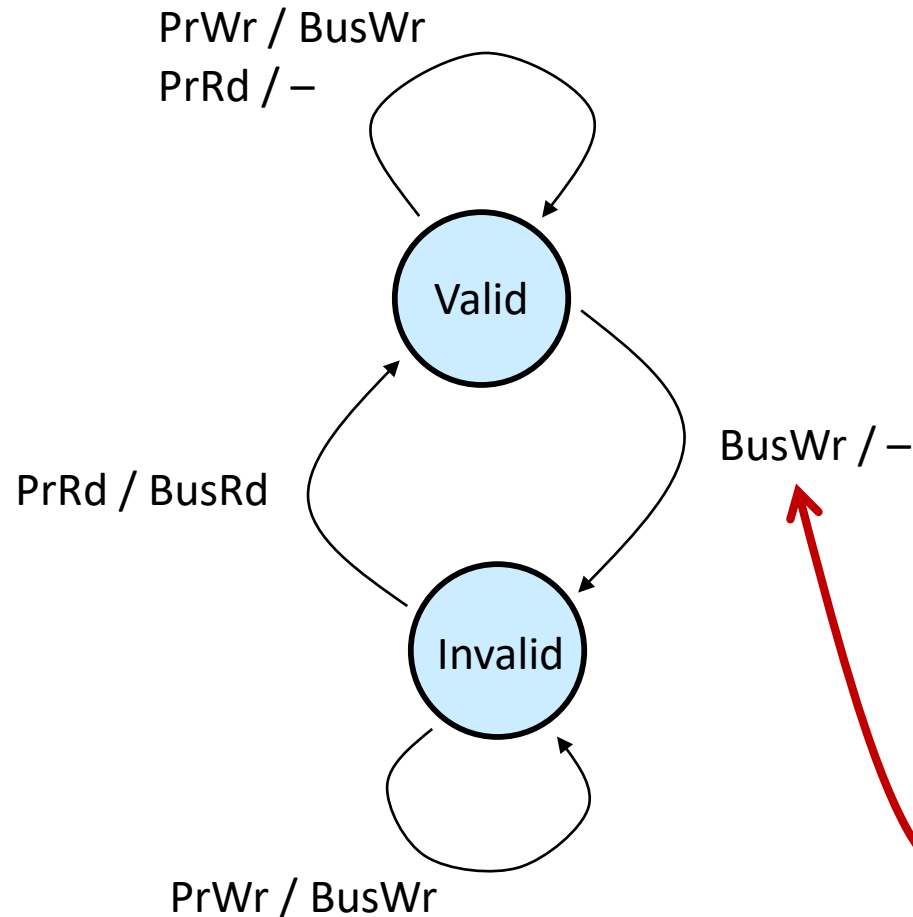
Step 4





- Write-through, write-no-allocate cache
- Actions:
 - PrRd
 - PrWr
 - BusRd
 - BusWr

Simple Invalidate Snooping Protocol

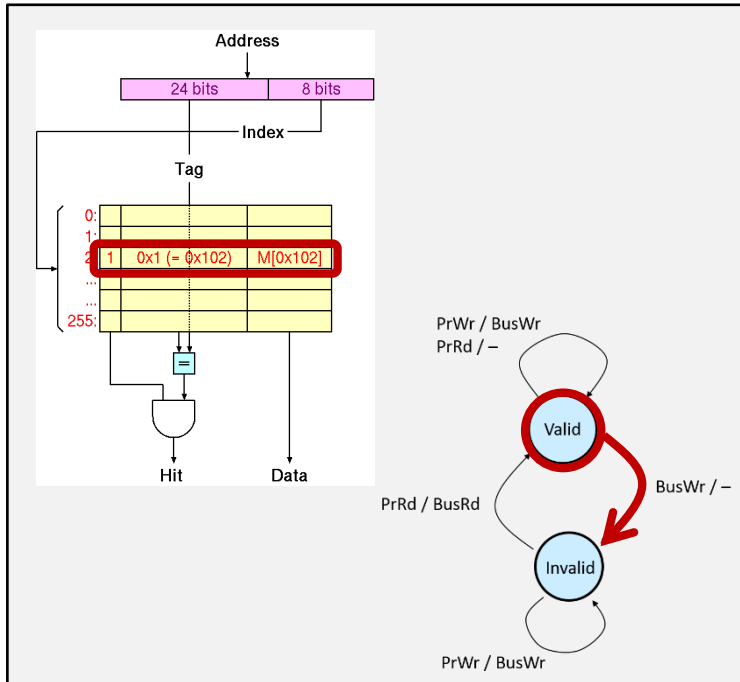


- Write-through, write-no-allocate cache
- Actions:
 - PrRd
 - PrWr
 - BusRd
 - BusWr

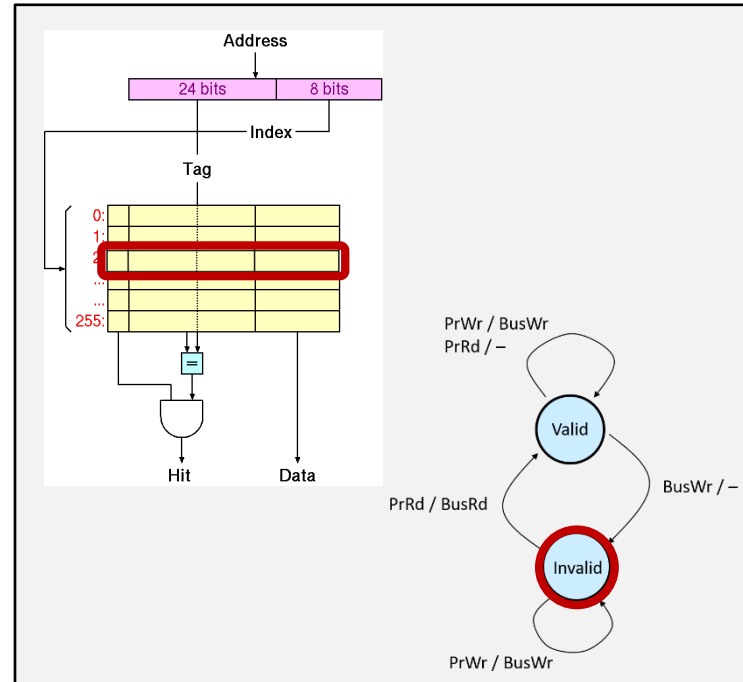
The cache **snoops** now!

Cache FSMs Work Simultaneously

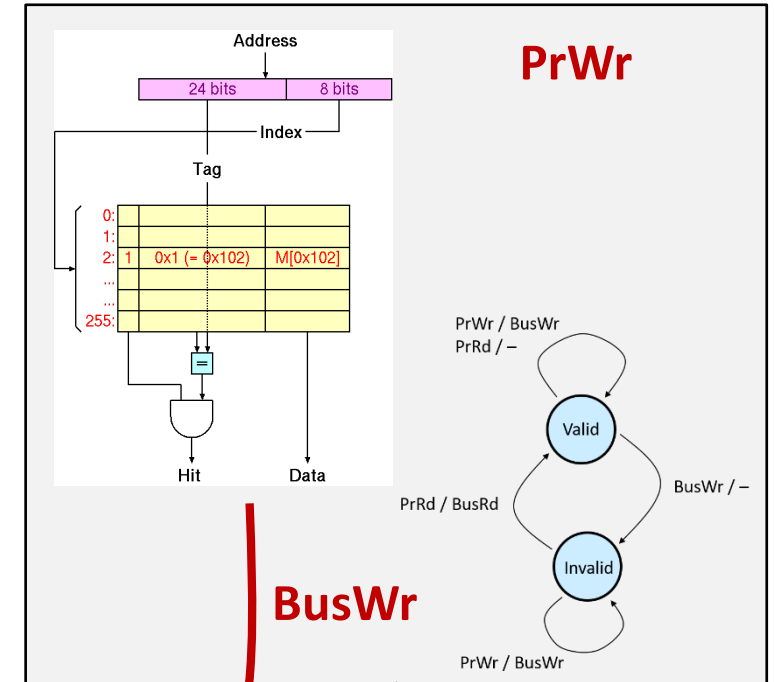
P1



P2

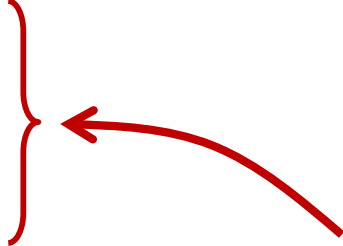


P3

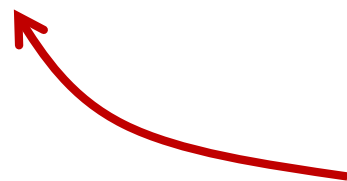


Memory

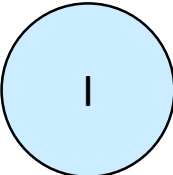
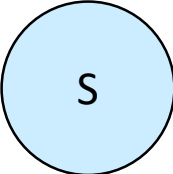
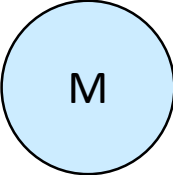
A 3-State Write-Back Invalidation Protocol (MSI)

- 2-State Protocol
 - Simple hardware and protocol
 - **Bandwidth (every write goes on bus!)**
 - 3-State Protocol (**MSI**)
 - **Modified**
 - Only one cache has valid/latest copy
 - Memory is stale, that is the content is not up-to-date
 - **Shared**
 - One or more caches have valid copy
 - **Invalid**
 - Must invalidate all other copies before entering modified state
 - Requires bus transaction (order and invalidate)
- 
- Functional issues **solved**
(caches are **coherent**)
but performance may be **abysmal!**

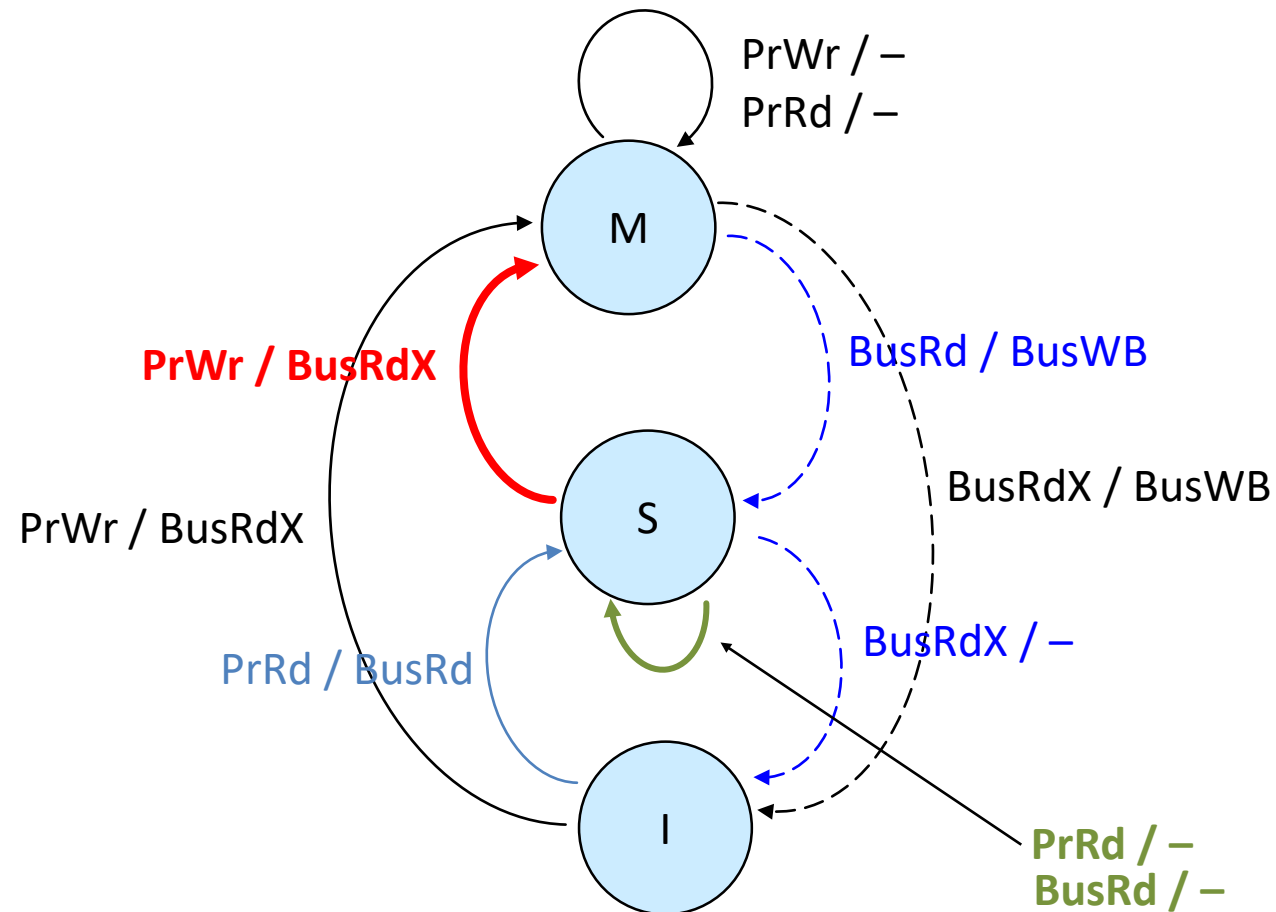
MSI: Processor and Bus Actions

- Processor
 - PrRd
 - PrWr
- Bus
 - **BusRd** (Bus Read) Read **without intent to modify**, data could come from memory or another cache
 - **BusRdX** (Bus Read Exclusive) Read **with intent to modify**, must invalidate all other caches copies
 - **BusWB** (Writeback) cache controller puts contents on bus and memory is updated
- Definition: **cache-to-cache transfer** occurs when another cache satisfies **BusRd** or **BusRdX** request with a **BusWB**
- Let's draw it!

A write to memory that can be simultaneously read also by other caches

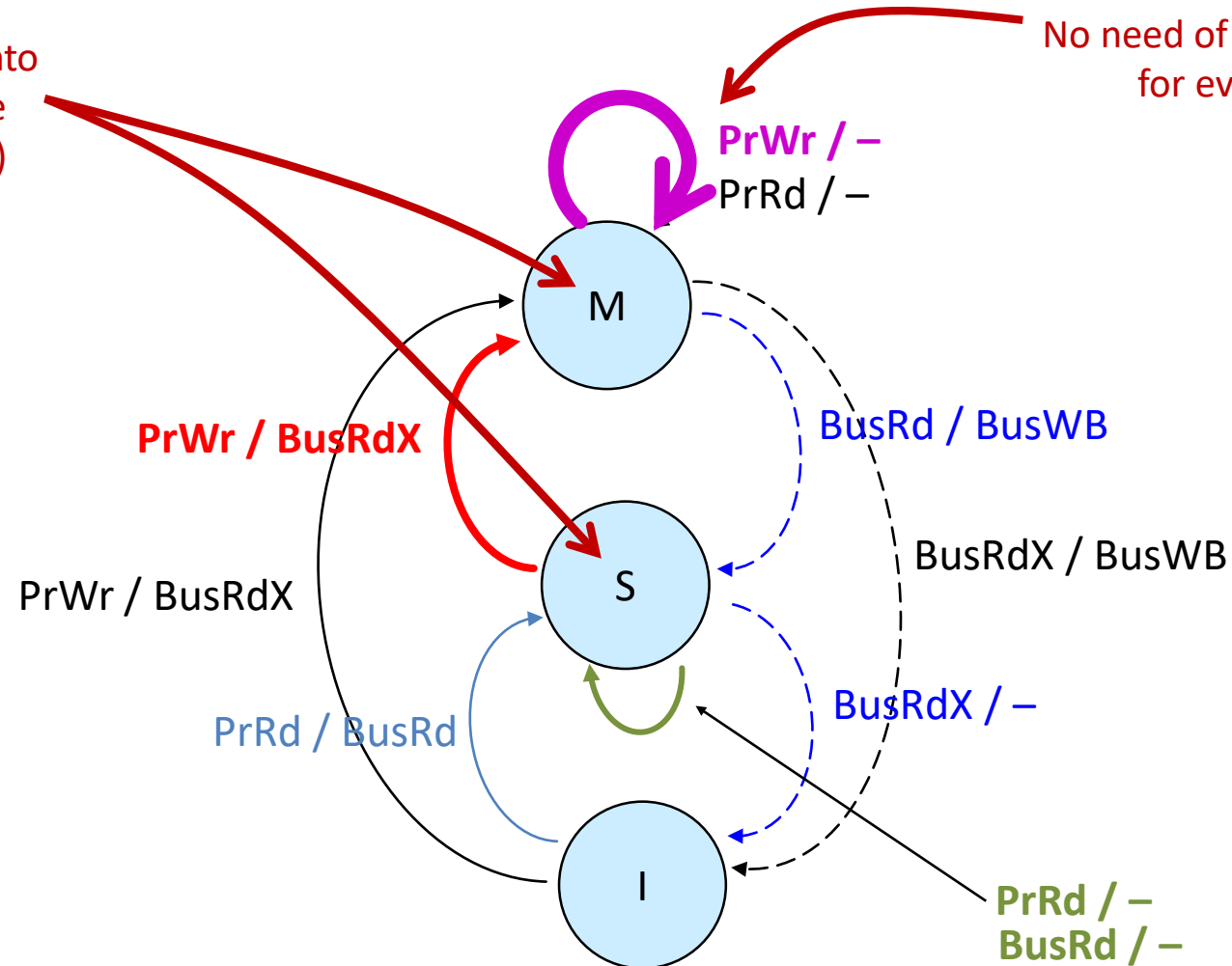


MSI State Diagram



What Has Changed?

We split the original **Valid** state into two states, one **Shared** and one **exclusive/dirty** (a.k.a. **Modified**)



Local variables cause
no memory traffic!

	CPU Action	P1 state	P2 state	P3 state	Bus Action	Data from
0		– (= I)	– (= I)	– (= I)		
1						
2						
3						
4						
5						

Example of MSI Transactions

	CPU Action	P1 state	P2 state	P3 state	Bus Action	Data from
0		– (= I)	– (= I)	– (= I)		
1	P1 reads x	S	– (= I)	– (= I)	BusRd	Memory
2	P3 reads x	S	– (= I)	S	BusRd	Memory
3	P3 writes x	I	– (= I)	M	BusRdX	Memory or not
4	P1 reads x	S	– (= I)	S	BusRd	P3's cache
5	P2 reads x	S	S	S	BusRd	Memory

4-State (MESI) Invalidation Protocol

- Often called the **Illinois** protocol
 - **Modified** (dirty)
 - **Exclusive** (unshared clean = only copy, not dirty)
 - **Shared**
 - **Invalid**
- Requires **shared** signal to detect if other caches have a copy of block
- Cache Flush for cache-to-cache transfers
 - Only one can do it though
- What does state diagram look like?

Many Other Similar Protocols

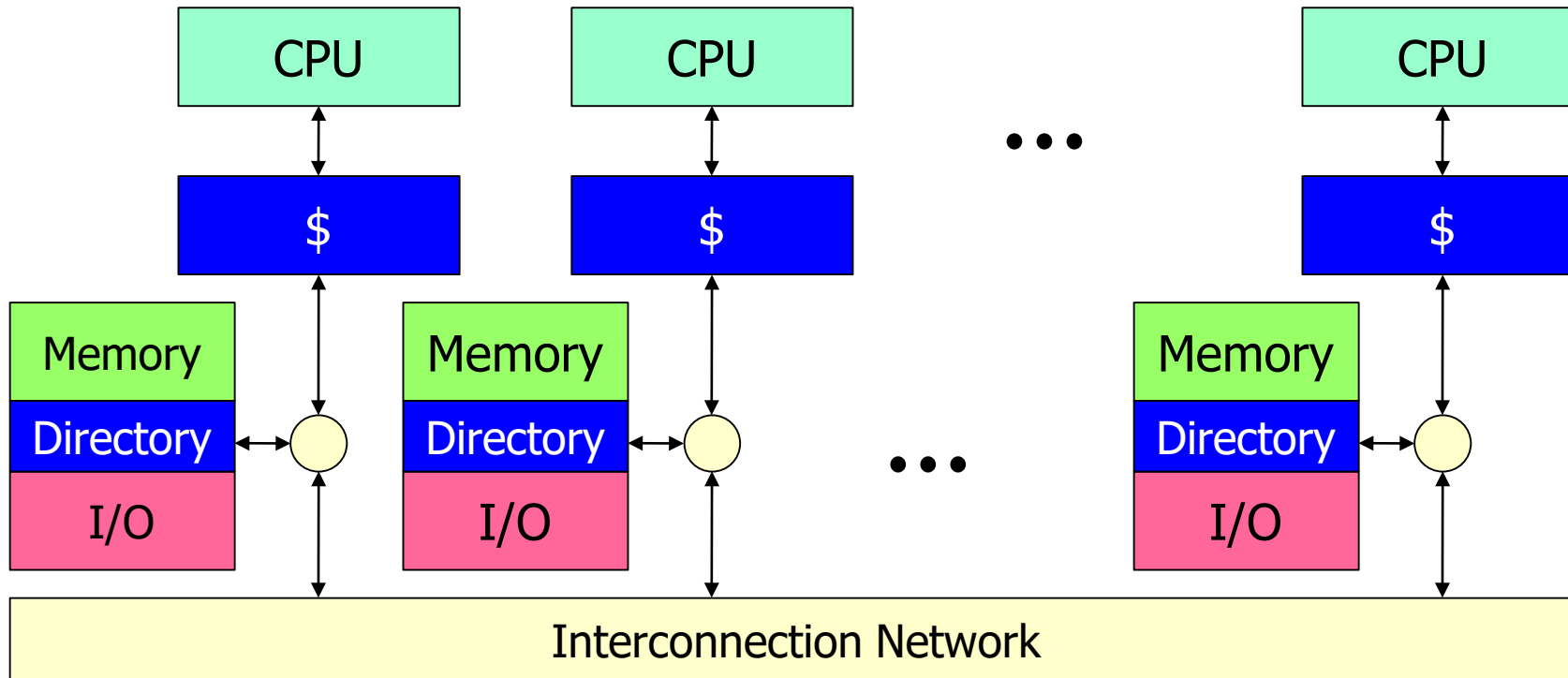
- More states, different transactions
- Lots of research on how to minimize the coherence traffic
(= better detect when it is not necessary)

An important problem is scalability
beyond a few processors/cores

→ **Directory-Based Cache Coherence**

Directory-Based Cache Coherence

- Typically needed in Distributed Memory Architectures



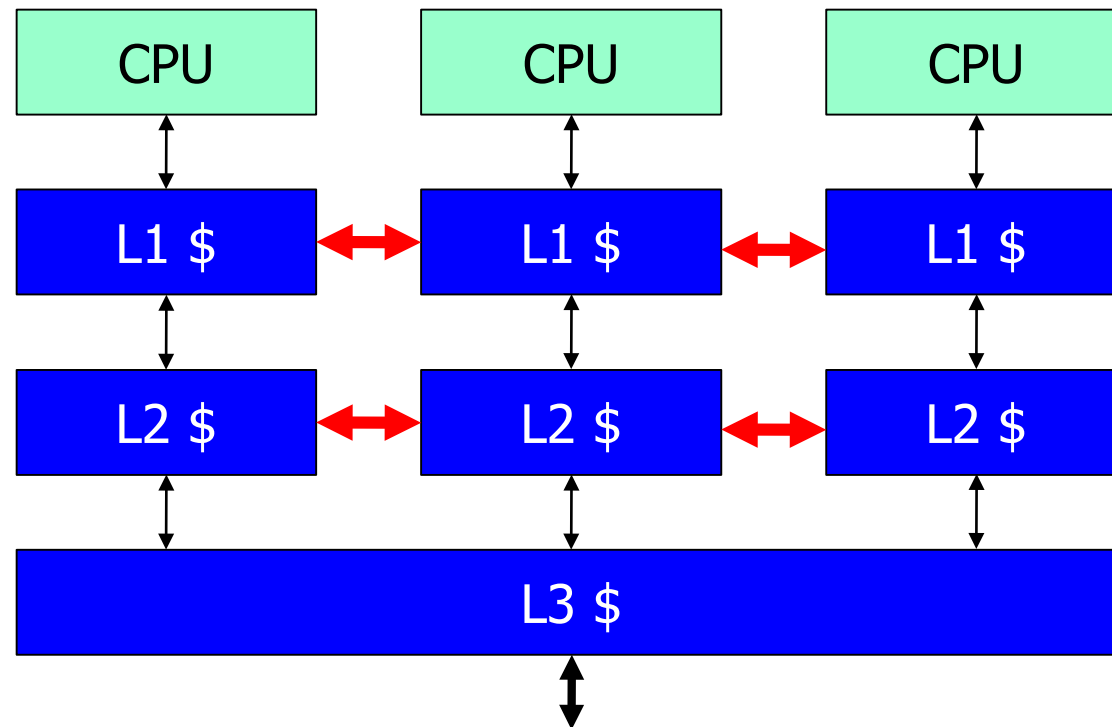
Directory keeps unique and “central” track
of existing cache copies and state

Snoopy vs. Directory-Based

- **Snoopy protocols** are distributed coherence protocols at the cache level
 - Scalability issues
 - Unnecessary coherence traffic
 - Fast
- **Directory-based protocols** are centralized protocols at the memory level
 - Scalable
 - Coherence traffic only as actually needed
 - Latency issues, due to centralization
 - Granularity issues, linked to latency issues

Multilevel Caches

- What happens if instead of **CPU** → \$ → **Mem** we have **CPU** → **L1 \$** → **L2 \$** → **L3 \$** → **Mem**?
- One could just replicate snooping at all levels



Inclusion Property between Caches at Levels $n-1$ and n

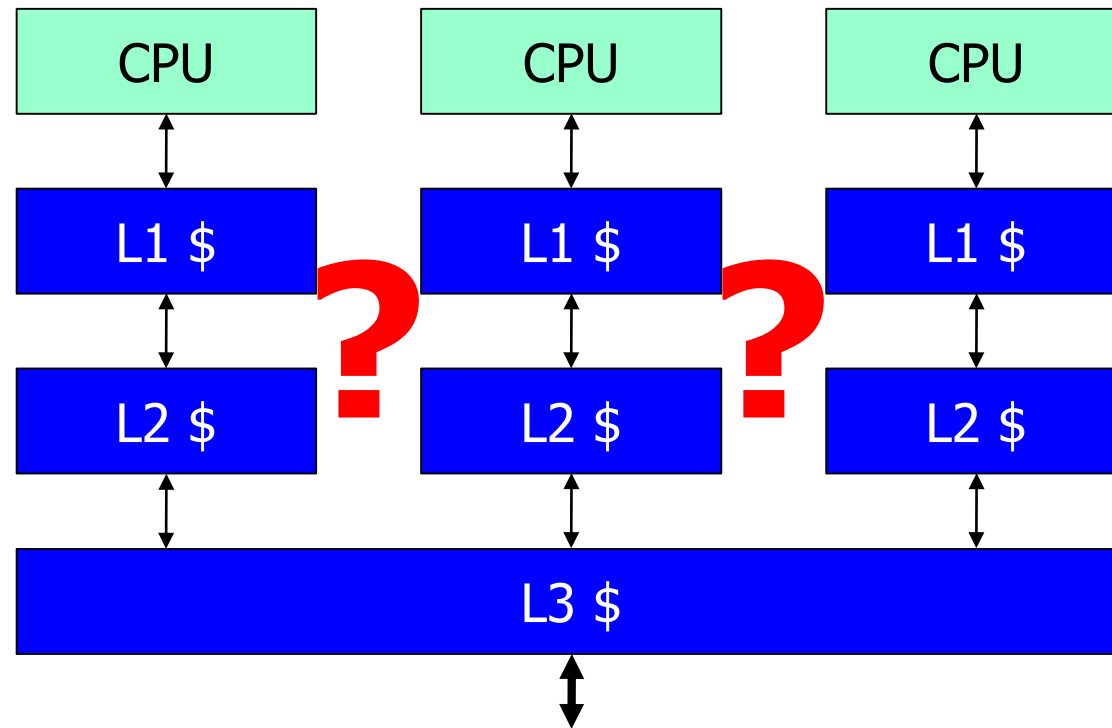
1. **Same content:** Content of $L(n-1)$ cache is always a subset of the corresponding $L(n)$ cache

A bus transaction from an $L2$ cache is also always relevant for the $L3$ cache, hence **a snoop at $L3$ is sufficient**

2. **Same state:** If a cache line is marked as owned/modified in $L(n-1)$ cache, then it should also be so marked in the corresponding $L(n)$ cache

If a bus transaction requests a cache line in owned/modified state in $L3$, the **$L3$ cache can determine this on its own without checking $L2$**

No Snooping Any More? Magic?

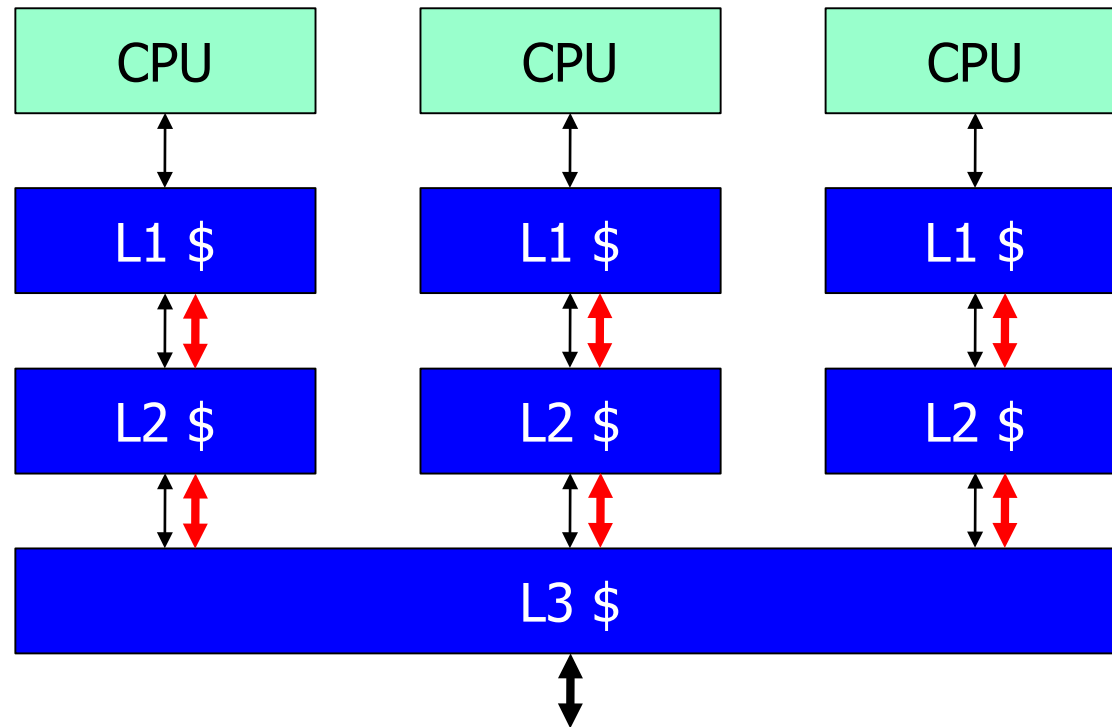


Is Inclusion Naturally Maintained?

- In some cases yes: in a Miss, it is, as L1 misses go to L2 and eventually the data will be in both
- In the general case **no**: for instance, L2 will eventually decide to evict a given line and that may be also in L1 → if nothing special is done, **inclusion will be violated**

Essentially, we will need to **propagate invalidations** and **evictions** up the hierarchy to keep, for instance, L1 informed of what happens in L2

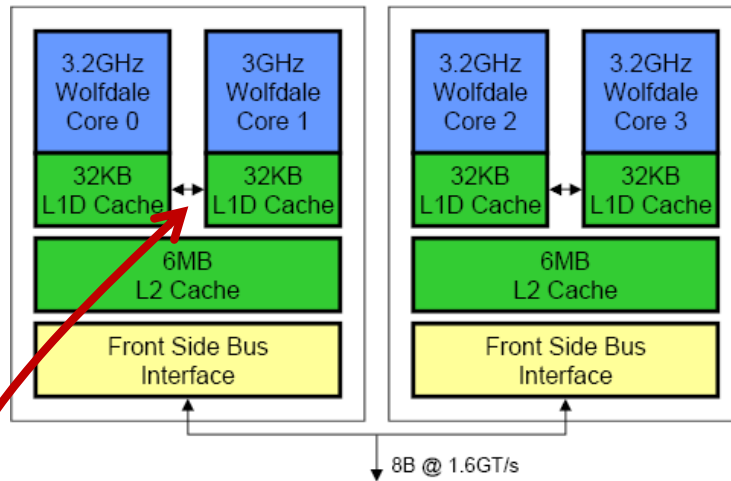
No Free Lunch! Only Different Messages



Which one is easier between snooping and maintaining inclusion is not trivially determined and well beyond this course...

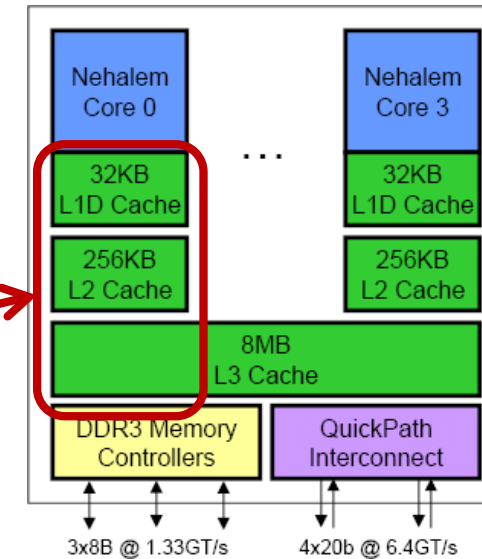
Intel Core and Intel Nehalem

Intel
Core



Snooping

Intel
Nehalem



Inclusion

References

- Patterson & Hennessy, COD – RISC-V Edition
 - **Sections 6.3** (SIMD & MIMD)
 - **Sections 6.5** (Multicores)
 - **Sections 5.10** (Cache coherence)